

#### Deadline Scheduler

Open Issues

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#### Who is Daniel?









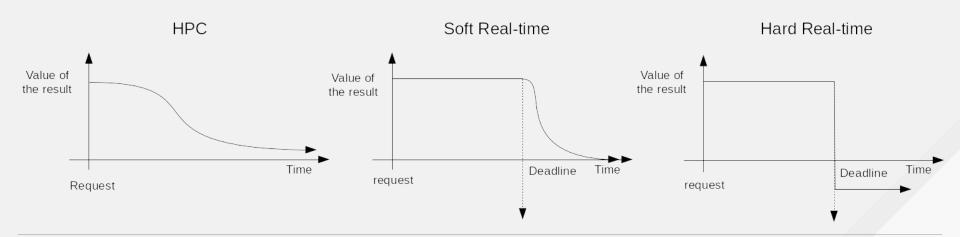
#### Real-time systems

Systems which deal with external events with timing constraints

- Real from real/external-world
- Time from timing constraints

The response of an event is correct if and only if:

- The logical response is correct
- It is produced within a deadline





#### Real-time scheduler modeling

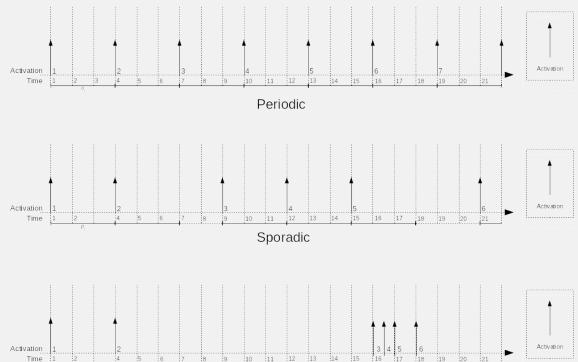
- A system is view as a "model"
  - A system is composed by a set of n tasks
  - A task is a set of infinity recurring jobs.
  - Each task is characterized by some parameters:
    - C or Q = WCET or Budget
    - Tor P = Period or Minimum inter-arrival time
    - D = Deadline



#### on Linux, DL tasks are characterized by:

- dl\_period = Period [sporadic | periodic]
- dl\_deadline = Relative deadline [ by default == period ... but can be < ]
- dl\_runtime = Execution time;

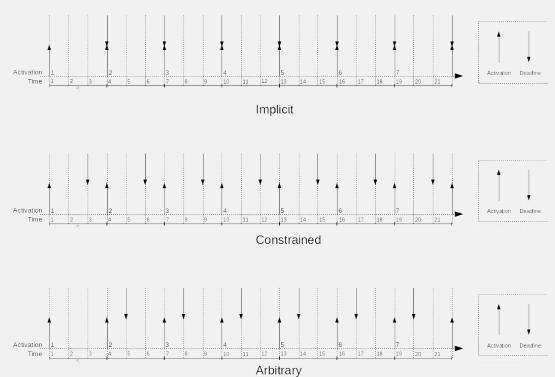
### Regarding Period:







#### Regarding Deadline:





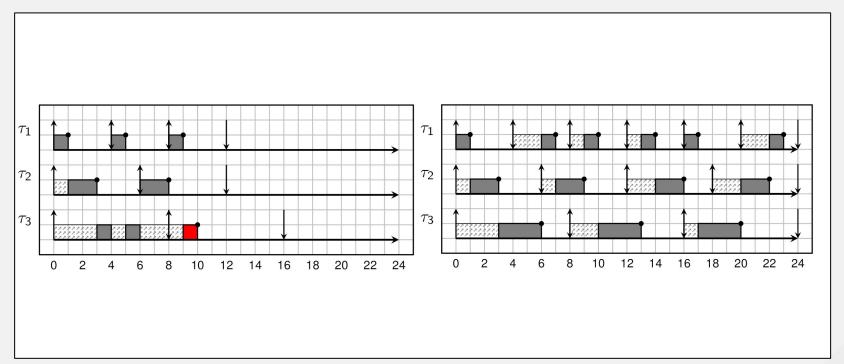
### Why EDF scheduler?



#### **Fixed Priority**

versus

#### Deadline





## EDF is optimal!

\*Under optimal conditions



#### EDF is optimal (U<=1) with

- If tasks does not misbehave
- Job does not suspend (dequeue/enqueue) during an activation
- Implicit deadline (deadline == period)
- Uniprocessor

#### Note:

```
[U]tilization = C/T (or Q/P, runtime/period)
[D]ensity = C/D (or Q/D, runtime/deadline)
```



## So, let's explore each point!

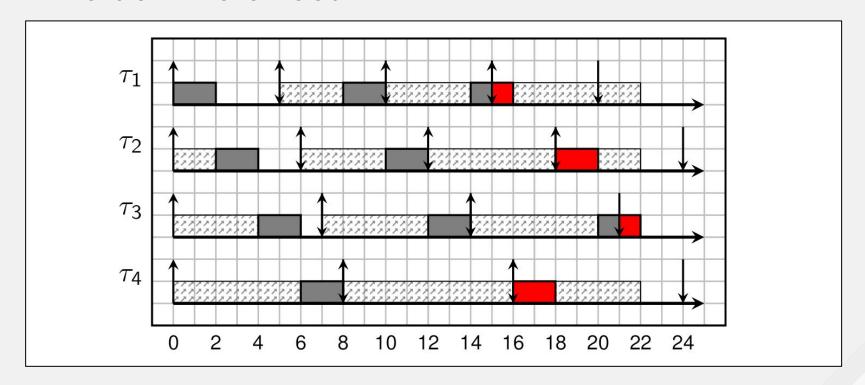


## What if a task runs longer than it said (C) it was suppose to run? Or

What if the utilization goes higher than 100%?



#### The domino effect





#### To avoid the domino problem...

- Admission control to avoid overload:
  - The sum of the Utilization of all tasks cannot be higher than rt\_period-rt\_runtime/rt\_period (by default 95%).
- CBS to avoid a misbehaving task to run more than runtime.



#### **CBS: Constant Bandwidth Server**

- Throttle a misbehaving task that uses more than allowed
- Try to provide runtime CPU time every period.
  - It relies on non-suspending tasks.



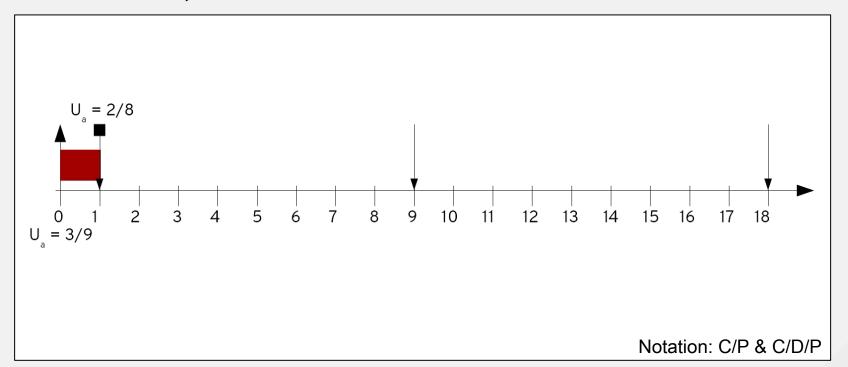
#### CBS & Suspending task

By assuming non-suspending tasks...

- It is implicitly assumed that, when queued, the absolute U of a task is bound to its relative U (U=runtime/period).
- In other words: The task will never overload the system.
- If the task suspends/blocks, that might not be the case...



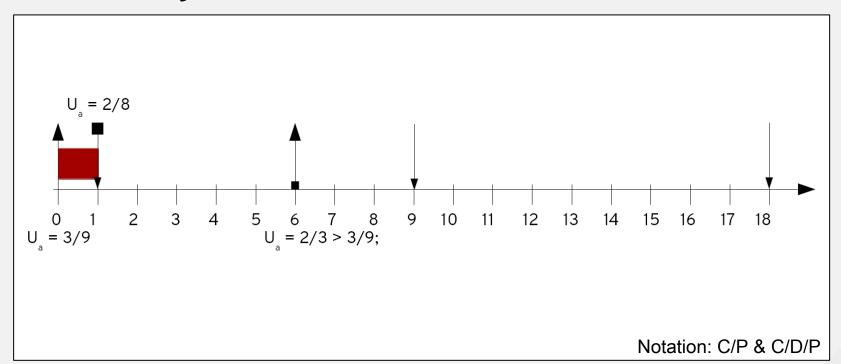
#### For example, a task with U = 3/9 blocks with 2/8







#### Returning with U=2/3



#### CBS & Self-suspending tasks

- CBS wakeup rule (ensures that a task will not overload the system):

If the **deadline** is in the **past**:

new absolute **runtime** and absolute **deadline** is set.

If the deadline is in the future:

If the possible U < allowed U

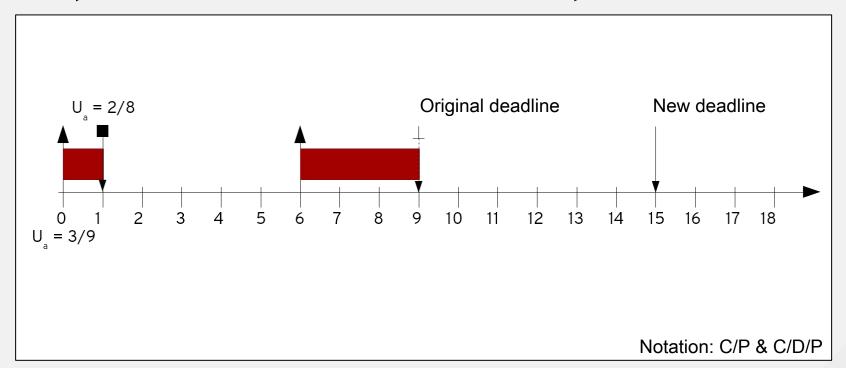
Go ahead and run, my little reservation.

else

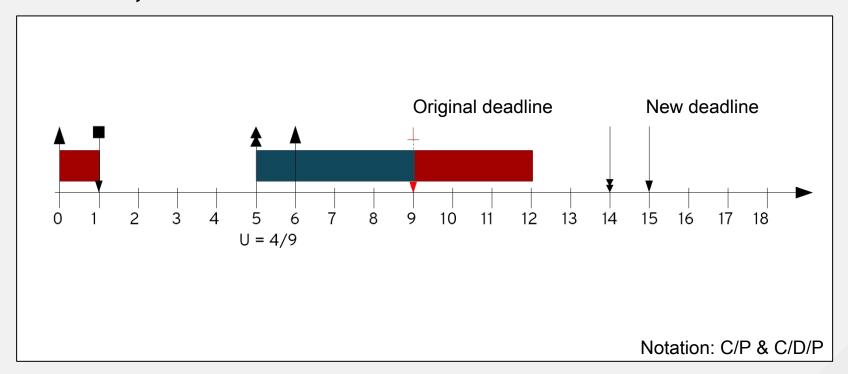
Reset runtime, set the new deadline



#### Replenish the runtime and reset period



#### In the presence of another deadline task...



# What do we care more, having runtime/period after a wakeup or try to make the deadline?



#### Revised CBS & Self-suspending tasks

- CBS wakeup rule (ensures that a task will not overload the system):

If the deadline is in the past:

new absolute runtime and absolute deadline is set.

If the deadline is in the future:

If the absolute U < relative U

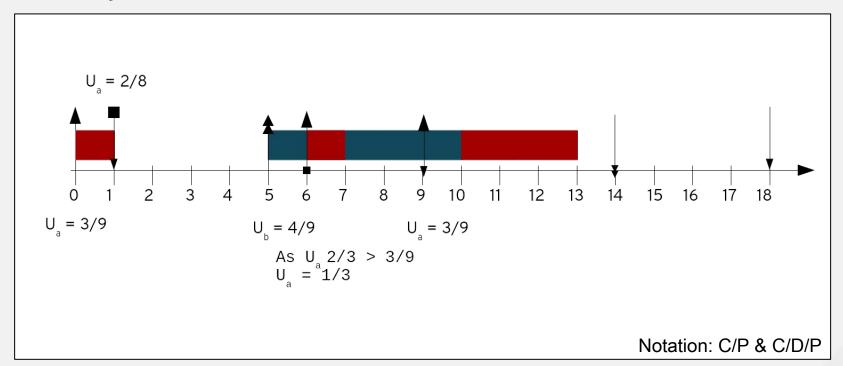
Go ahead and run, my little CBS.

else

Truncate runtime, new runtime = (C / P) \* laxity



#### Using the revised CBS:

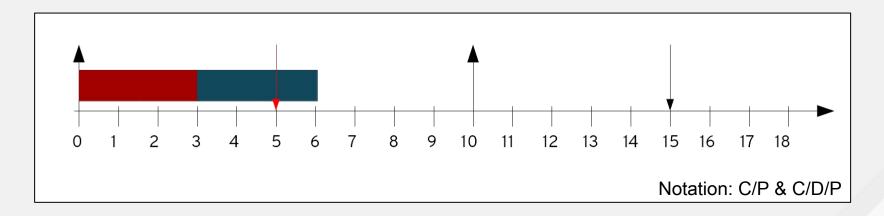




# Should we consider using the revised CBS?

#### Constrained deadline

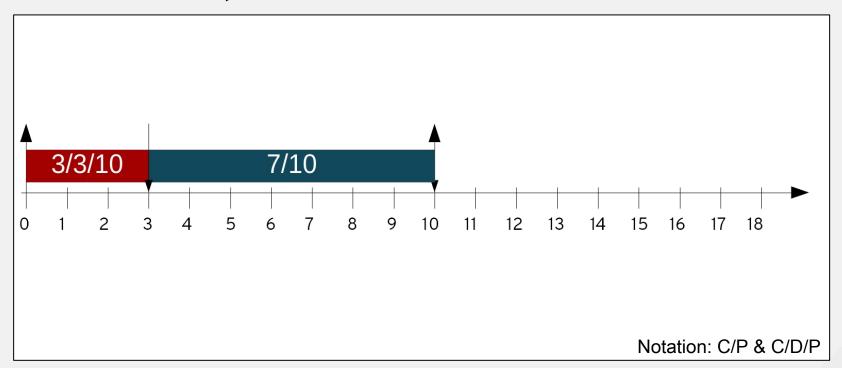
- Linux's deadline scheduler accepts task with deadline <= period.
- In the presence of an !implicit deadline task, the admission test is not valid to "guarantee" the deadline, even on single-core systems.
- For example, two tasks with 3/10 (60%) but deadline of 5:



# That is easy! We should use runtime/deadline, not runtime/period!



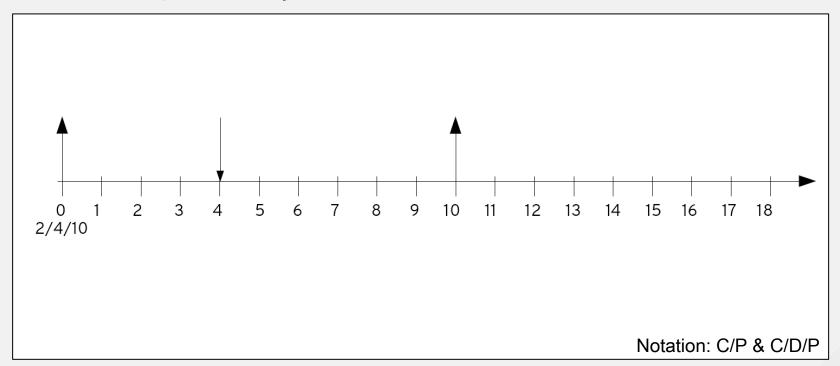
#### No, it is too pessimistic...



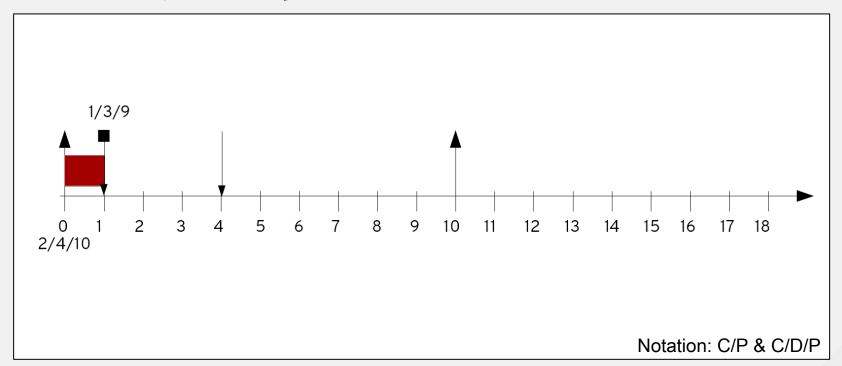


# There is one case in which we decided to use it, with revised CBS...



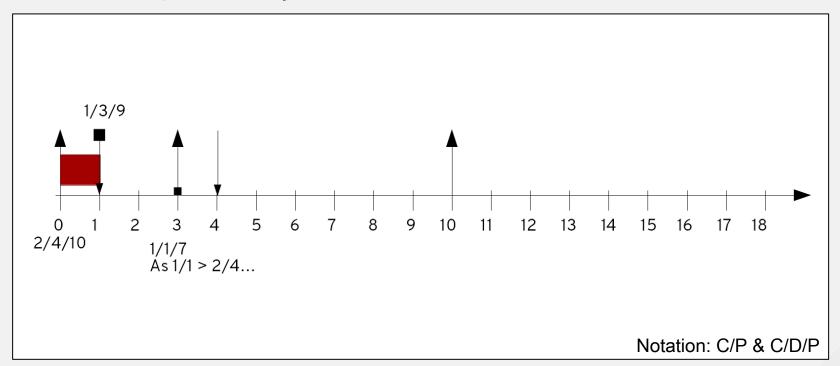




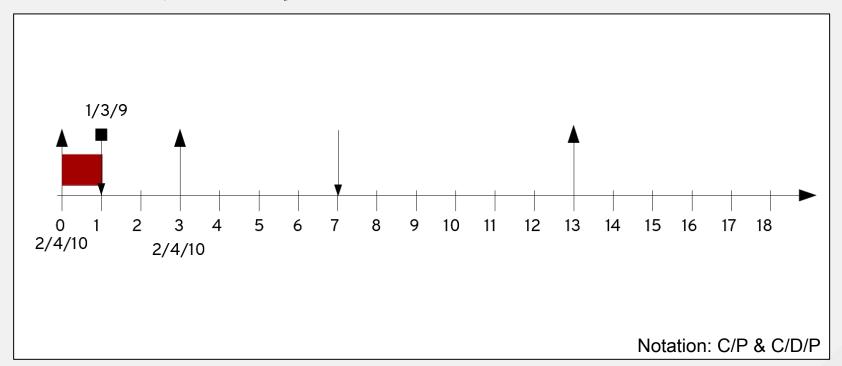




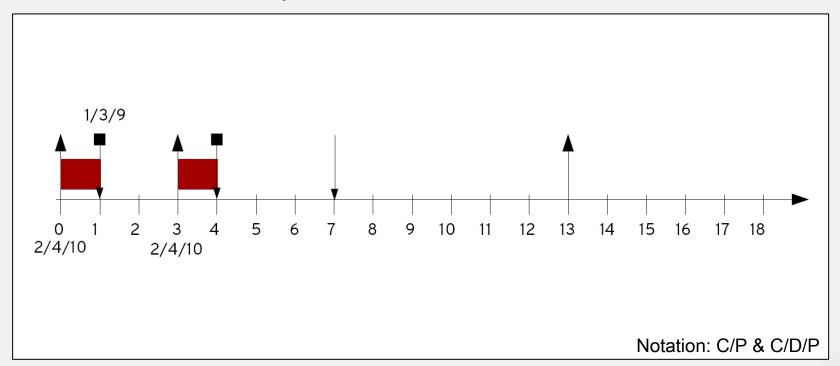




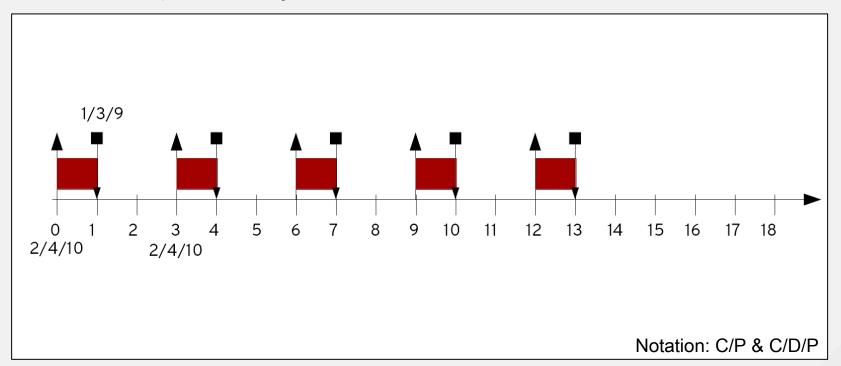














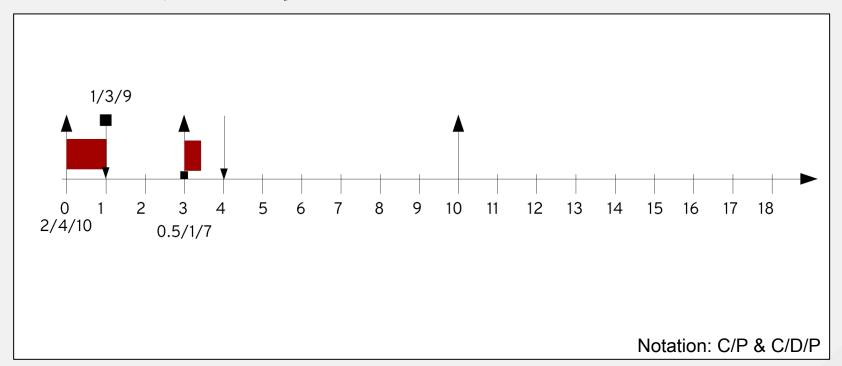


#### Revised CBS & Suspending & Constrained DL

```
- CBS wakeup rule (ensures that a task will not overload the system):
    If the deadline is in the past:
         If the next period is in the future:
             Throttle waiting the next period;
         else
              new absolute runtime and absolute deadline is set.
    If the deadline is in the future:
         If the absolute Density is < relative Density
             Go ahead and run, my little CBS.
         else
             Truncate runtime, new runtime = (C / D) * laxity
```



#### Self-suspending constrained deadline task





# Mamma mia! Things are confuse for deadline < period & Self-suspending!?!?!?!

# Suspending + constrained deadline is a REAL open issue.



# Let's talk about multi-processor scheduling

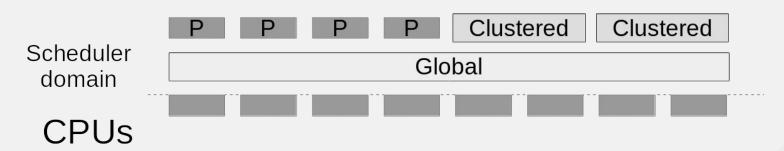




#### Multi-processor scheduling

a scheduler can be classified as:

- Partitioned: When each scheduler manages a single CPU
- Global: When a single scheduler manages all M CPUs of the system
- Clustered: When a single scheduler manages a disjoint subset of the M CPUs
- a CPU cannot belong to two "domains".





## Let's talk about global scheduling!





#### Global scheduling

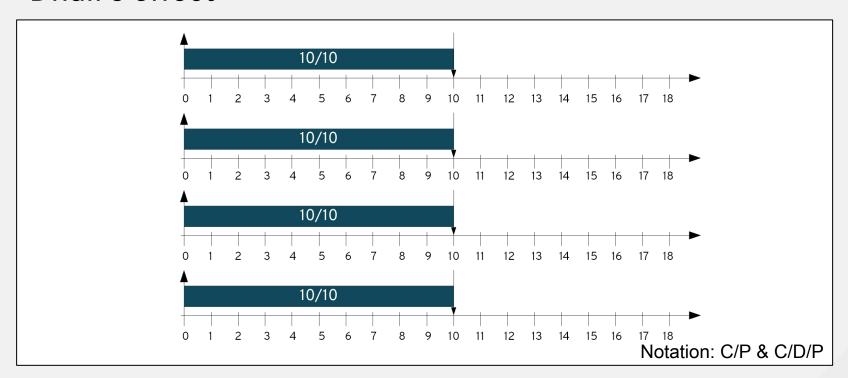
Global scheduling adds a lot of anomalies.

For instance, there is no critical instant.

- Release all tasks at same time is not the worst case anymore
- "Obvious things" are not obvious anymore:
  - Reducing the load of a schedulable taskset does not turn guarantee the task set will still schedulable...

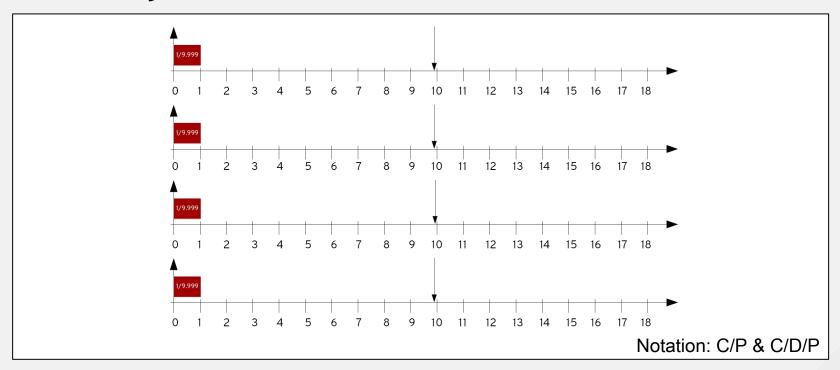


#### Dhall's effect

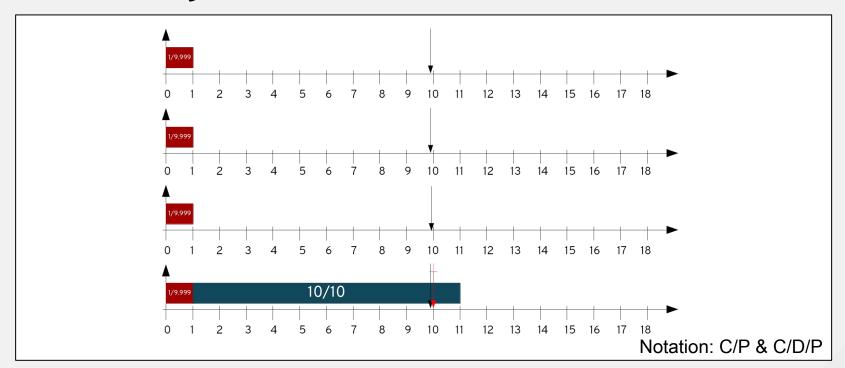




#### Reducing the load...



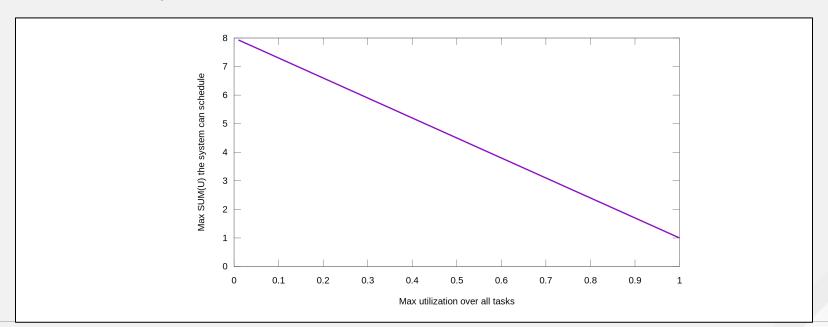
#### Increasing a little bit... BOOM!





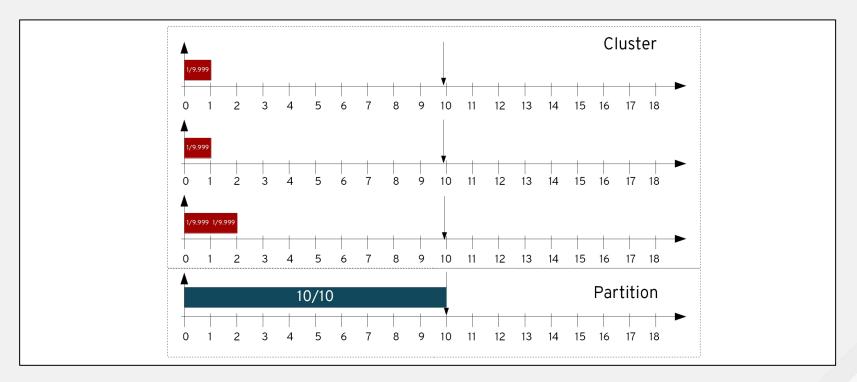
#### Taking Dhall's effect in account, an admission test would be:

- $\sum (U) \le M (M 1) * U_{max}$
- Where U<sub>max</sub> is the highest U of all tasks





#### Solution: Partitioned + Clustered





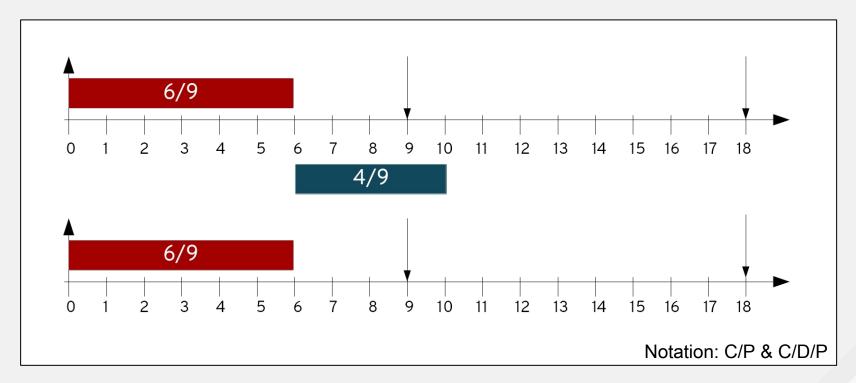
# What if those small tasks were per-cpu tasks?



## So should we always use partitioned?



#### How about this scenario?





# Neither partitioned nor global are optimal...



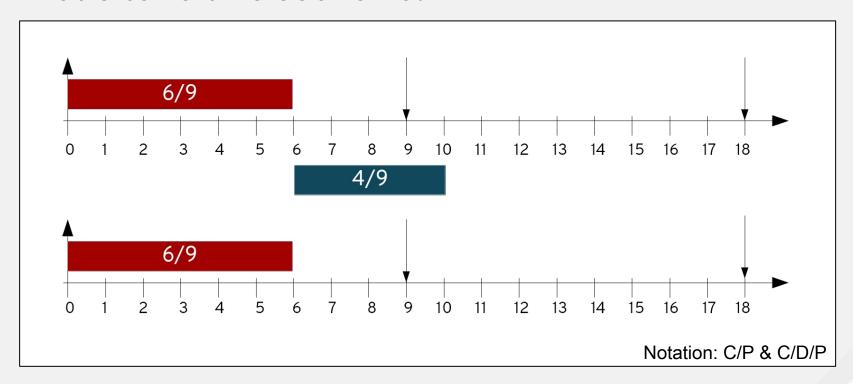
# Is there anything else we could?



# The word is: semi-partitioned

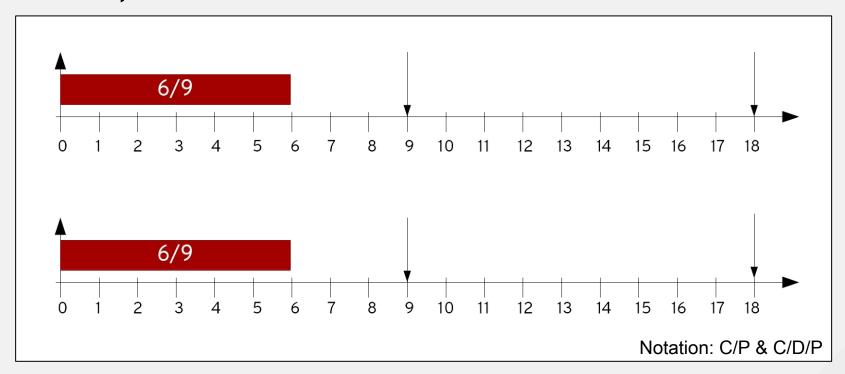


#### Let's take this scenario:



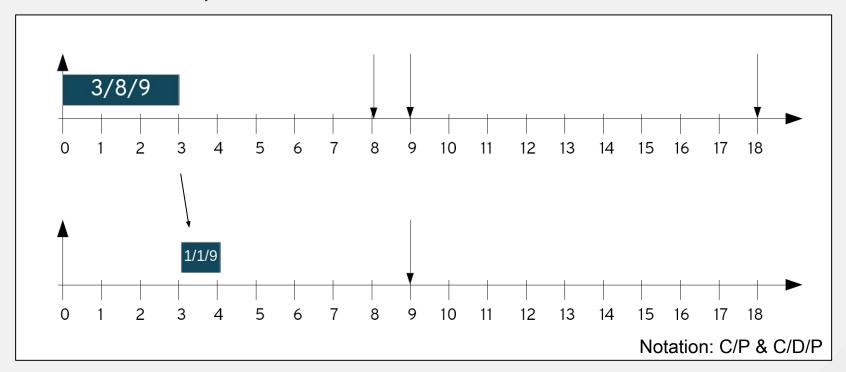


#### Let's pin some tasks:





#### Then, we split the other one....

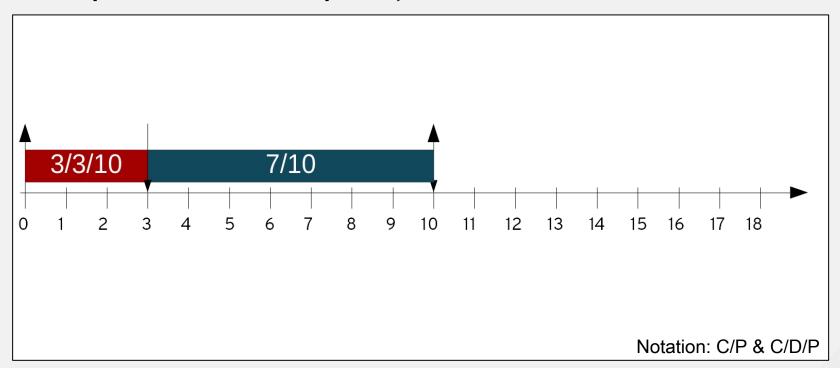




# Hey hey hey! Didn't you say constrained deadline tasks are a problem?

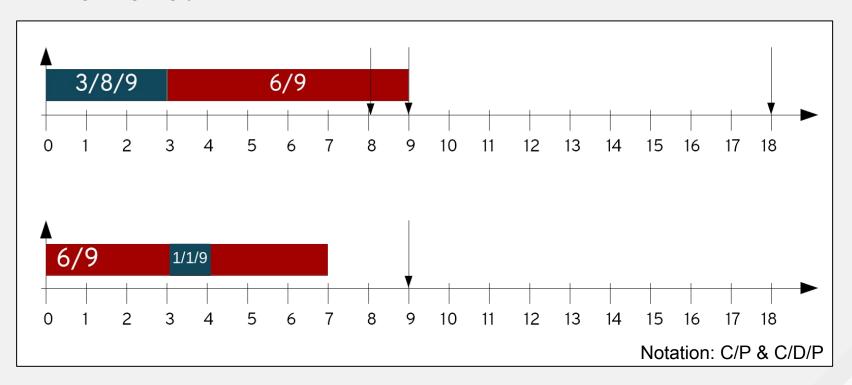


#### They are not always a problem:





#### And voilà!





# How good is this idea?



#### B. Brandenburg and M. Gül

Global Scheduling Not Required: Simple, Near-Optimal Multiprocessor Real-Time Scheduling with Semi-Partitioned Reservations:

> "Empirically, near-optimal hard real-time schedulability — usually ≥99% schedulable utilization can be achieved with simple, well-known and wellunderstood, low-overhead techniques (+ a few tweaks)."

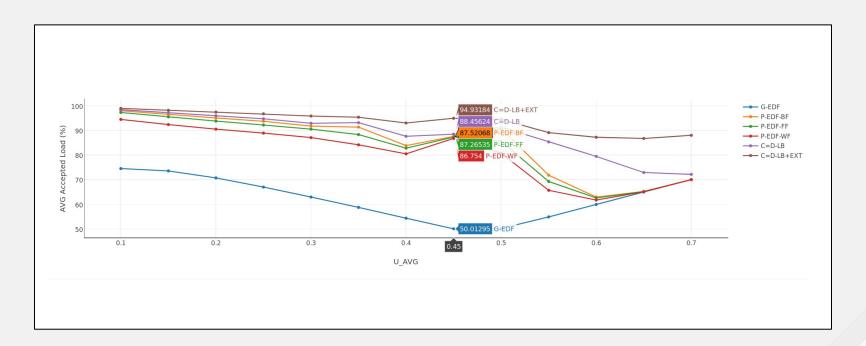


#### Daniel Casini, Alessandro Biondi, Giorgio Buttazzo

Semi-Partitioned Scheduling of Dynamic Real-Time Workload: A Practical Approach Based on Analysis-Driven Load Balancing.

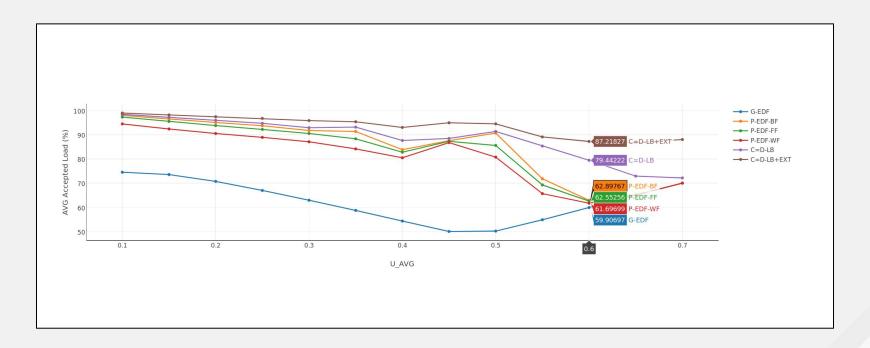


#### Online semi-partitioned comparison:





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#### Affinity! For almost free

Affinity for global scheduling is a problem For semi-partitioned... it is not.

- Just one more input to the heuristics
- Possible to make a "per-cpu fake load" to reserve time for CFS
- DL Server to schedule CFS: Hierarchical scheduler
  - A re-implementation of RT Throttling:
    - [PATCH] sched/rt: RT\_RUNTIME\_GREED sched feature
    - https://lkml.org/lkml/2016/11/7/55



### We still have arguments for another talk



# But I am being throttled...



## Questions?





## Thank you! Obrigado! Grazie Mille!



